

Stopper Cylinder EC-ST15

Features

- Ideal as a workpiece-stopper on a conveyor line without air source.
- Workpieces up to 50kg.
- Maximum collision speed of workpiece: 40m/min. (in case of 9kg workpiece)

| Product model number | | |
|----------------------|--------------|--|
| Product model n | umber | |
| EC-ST15 | | |
| | | |
| Cable length | | |
| Cable code | Cable length | |

| Cable code | Cable length |
|------------|------------------------------------|
| 0 | without cable (connector included) |
| 1~3 | 1 ~ 3m |
| 4~5 | 4 ~ 5m |
| 6~10 | 6 ~ 10m |

Main specification

| Lead | | Ball screw lead (mm) | 3 |
|--------------------|-------------------------|---------------------------------------|--------------------------------------|
| | Payload (Note 2) | Payload (kg) (power-saving disabled) | 5 |
| | | Maximum speed (mm/s) | 200 |
| | | Minimum speed (mm/s) | 4 |
| | | Rated acceleration/deceleration (G) | 0.3 |
| | | Maximum acceleration/deceleration (G) | 0.5 |
| Vertical Speciacce | Payload (Note 2) | Payload (kg) (power-saving disabled) | 3 |
| | Speed/ acceleration/ | Maximum speed (mm/s) | 200 |
| | | Minimum speed (mm/s) | 4 |
| | deceleration | Rated acceleration/deceleration (G) | 0.3 |
| | | Maximum acceleration/deceleration (G) | 0.5 |
| Brake | | Brake specification | non-exciting electromagneticbrake |
| | | Brake-holding force (kgf) | 12.5 |
| Stroke (mm) | | | 50 |

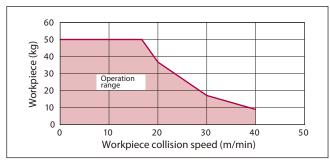
| Options | | |
|--|-------------|--|
| Name | Option code | |
| Brake | В | |
| Non-motor end specification | NM | |
| PNP specification | PN | |
| Twin power supply specification | TMD2 | |
| Battery-less absolute encoder specification | WA | |
| Wireless communication specification | WL | |
| Wireless axis-operation specification | WL2 | |
| (Note 1) The home position of the standard specification is set on the non-motor side. | | |

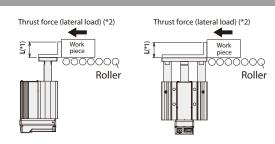
Note 1) The home position of the standard specification is set on the non-motor sid Refer to the dimension drawing on back side for the home position.

| Driving method | Ball screw Φ10mm, Rolled C10 | |
|---|---|--|
| Positioning repeatability | ±0.15mm | |
| Rod | Φ25mm, Material: aluminum, hard alumite treatment | |
| Guide shaft | S45C | |
| Front bracket | \$45C | |
| Ambience operating temperature & humidity | 0~40°C, 85%RH or less (non-condensing) | |
| Degree of protection | IP20 | |
| Vibration and shock resistance | 4.9m/s ² | |
| Overseas standard | CE Marking, RoHS | |
| Motor type | Stepper motor | |
| Encoder type | Incremental / Battery-less absolute | |
| Number of encoder pulses | 800 pulse/rev | |



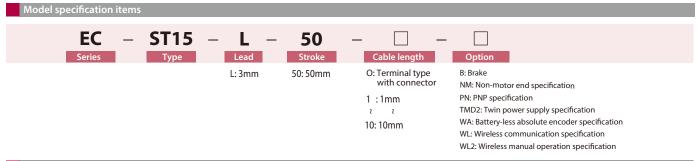
Chart of the correlation between mass and collision speed of the workpiece





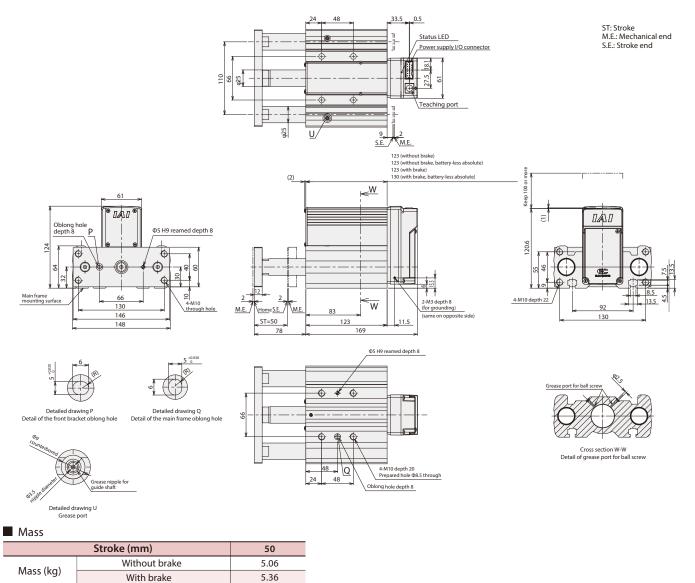
(*1) Use within the dimension L=50mm or smaller. (*2) Allowable load of the thrust force by conveyor should be 500N or smaller.





Dimensions

(Note) When performing a home return, the rod moves to M.E. Beware of possible interference with peripheral equipment.



Controller

* The EC series is equipped with a built-in controller. Refer to the ELECYLINDER catalog for the details of the built-in controller.

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